ITN-DCH www.itn-dch.eu





MAGDA RAMOS CALLES, ESR2

Career Development Plan

Long-Term Objectives:

- Develop innovative data fusion methods and algorithms
- Exploit the intrinsic advantages of raw data, merging image and range information
- Realize cost-effective tools for cultural

heritage digitalization

Strengthen the integration of photogrammetric and computer vision techniques

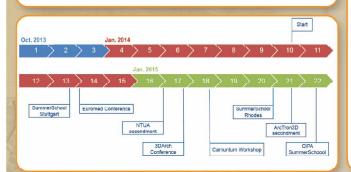
Short-Term Objectives:

- Data fusion state-of-the-art
- Collaboration in projects related to fusion
- Training in specific new areas

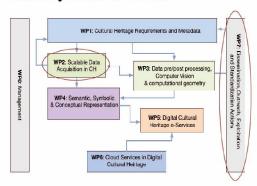


Training Activity

I have actively participated in several training activities of the ITN-DCH project: Summerschool. WorkShop. Conference and Secondment; and some additional like 3DArch Conference.



ITN-DCH Project Involvement



Contribution to: deliverables D 1.1, D 2.1 and D 2.2; Consortium Newsletter & diffusion at the social media

Image - CRP

Research Activity Data Fusion State-of-the-Art

Comparative range & image-based:

	Range - TLS	Image - CRP		
ACQUISITION - FIELD WORK				
Portability	Low	High		
Network design	Fixed stations	Easy to move station positions, and to have redundancy taking more shots		
Target/spheres/markers (several stations)	Required	Not necessary, only to improve orientation		
Acquisition time	Depends on the number of stations and ordusions	Measure the reflected light from objects (color, texture), ambient light need to be controlled knough coverage		
Ambient light	Independent			
Kequirements for 3d [several stations)	largets and/or control points need to appear in several scan stations			
Radionic tric resolution	Low, docreto	Continuous		
Noise (moving obstacles)	Hgh	Low		

	Range - TLS	Image - CRP		
PROCESSING				
required (to obtain the complete 3d point cloud)	Cloud registration (several stations)	Internal and external orientation Bundle-adjustment Dense matching		
Suf (ware	Proprietary (mesh registering)	Open source solutions for academic an non- commercial use		
Derive 3d information	Directly	Computation required to obtain 3d coordinates		
Color mapping/texture quality	Low, discrete	High continuous		
	No, depends on the footprint and its location			
Scale	11	Need to be scaled		

			coordinates	Suitable for (based		Line-based surfaces
	Color	Low, discrete	High, continuous	on time required)	irregular surfaces	
	mapping/texture quality			surfaces		Yes
	detection, structural parts	No, depends on the footprint and its location		Underwater applications	Only triangulation scenners (low field of view)	
Data	Scale	11	Need to be scaled	Fast moving objects	No	Yes
types:	SATELUTE	AERIAL T	ERRESTRIAL	GNSS	Data fusior	n levels:
	IMAGES	DATA	1	POGRAPHIC	PURPOSE-BAS LEVELS:	ED MEDIUM-LEVEL HIGH-LEVEL
(HDR	<i>y</i> / ×	TEGRATION NEEDL	S. Marie	~-~	/ POINT-BA	SED
MULTI &	SCAN	NER -	1/6		BASED FEATURE	
HYPERSPECT	ToE (timo)	TRIANGULA		Drawinge)		/3D to 3D
	phase	Full Waveform	UCTURED LIGHT		LEVEL	
		LIDAR				

Future Work

- ArcTron3D: Secondment
- CIPA SummerSchool: Dissemination
- CIPA Symposium: Paper Presentation
- Stuttgart Univ.: Secondment
- PhoWo: Training

Research:

- Thermal Calibration & Registration
- Data fusion SOTA
- Strengthen pho & computer vision







Host Country



Sommarive, 18 38123 Irento www.3dom.fbk.eu

Host Organization







This project has received funding from the European Union's Seventh Framework Programme for research, technological development and demonstration under grant agreement no 600013.